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OF THE ON-SHELL PHASE FUNCTION

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#### ABSTRACT

The Karlsson-Zeiger three-body equations work exclusively with half-off-shell scattering amplitudes as two-body input. The half-off-shell phases, themselves, can be calculated by solving Sobel's non-linear differential equations. Present paper proposes an explicit form for the half-shell phase in terms of the on-shell phase functions, i.e. just the solution to the Sobel equation, in any partial wave.

#### **РИДИТОННА**

Трехчастичные уравнения Карлсона-Зейгера работают исключительно с двухчастичными амплитудами рассеяния частично вне массовой поверхности. Решением нелинейного уравнения Собеля можно получить эти фазовые сдвиги. В настоящей работе выведено явное выражение для фазовых сдвигов частично вне массовой поверхности через фазовые функции на массовой поверхности.

## KIVONAT

A háromtest-szórási probléma Karlsson és Zeiger által ujonnan felállitott integrálegyenletei a két.test inputot kizárólag félig-off-shell amplitudók formájában tartalmazzák. A félig off-shell fázistolások a Sobel által korábban felállitott fázisegyenletek megoldásából nyerhetők. Jelen cikk explicit és exakt megoldást ad Sobel nem-lineáris differenciálegyenletei számára.

## 1. TWO-BODY INPUT TO THREE-PARTICLE PROBLEMS

Barring three- and many-body forces, the N-particle dynamics is governed by the elementary interaction through the two-particle transition matrix  $t(k_0^2+i\epsilon)$ . Concerning case N=3, as far as only the Faddeev-equations [1] were available, knowledge of all the off-the-energy shell matrix elements  $t(k_2, k_1; k_0^2)$  was considered to be necessary to supply the two-body input for the three-particle theory. Calculation of the completely off-shell two-particle scattering amplitudes in terms of the potential V(r) consists in solving integral equations of the Schwinger-Lippmann type. The partial wave t-matrix elements satisfy the equation [2]

$$t_{\ell}(k_{2},k_{1};k_{0}^{2}) = V_{\ell}(k_{2},k_{1}) + \frac{2\mu}{\hbar^{2}} \int_{0}^{\infty} q^{2} \frac{V_{\ell}(k_{2},q)t_{\ell}(q,k_{1};k_{0}^{2})}{k_{0}^{2} - q^{2}} dq$$
 /1.1/

with the notation

$$V_{\ell}(k,q) = \frac{1}{(2\pi)^3} \int_{0}^{\infty} r^2 \hat{j}_{\ell}(kr) V(r) \hat{j}_{\ell}(qr) dr$$
 . /1.2/

When solving eq. /1.1/, one has to face, in fact, double integrations. The early modifications of the Faddeev-equations [3] require invariably the completely off-shell two-body input for the three-particle problem. Only recently, Karlsson and Zeiger [4] succeeded in transforming the three-body Faddeev equations in such a way that the new system of integral equations involves as two-body input exclusively the half-off-shell amplitudes  $t(k_2,k_1;k_1^2)$  (for all momenta  $k_2$  and  $k_1$ ) and the bound state vertex functions.

Whether the Karlsson-Zeiger equations come up to essential simplifications in the three-body calculations depends critically on the easy availability of the half-shell scattering amplitudes. A simple recourse to eqs. /1.1/-/1.2/ for case  $k_0=k_1$  would not offer significant time saving on the computer in comparison to the conventional calculations. Nevertheless, there is also a more promising approach to the half-shell amplitudes. Within the framework of the variable phase approach [5,6] as developed by Calogero and coworkers, Sobel derived [7,8] non-linear differential equations for the two-particle half-off-shell phase functions in any partial wave working with the

on-shell phase functions as input. Sobel's phase equation reads for the special case of S-waves as

$$\frac{d\Delta_{O}^{(211)}(a)}{da} = -V(a) \sin[k_{1}a + \delta_{O}(k_{1}, a)]$$

$$\{k_{2}^{-1} \sin(k_{2}a) + k_{1}^{-1} \cos[k_{1}a + \delta_{O}(k_{1}, a)] \Delta_{O}^{(211)}(a).$$

Here, function  $\Lambda_{O}^{(211)}(a)$  is defined by the identity

$$e^{i\delta_{O}(k_{1},a)} \Lambda_{O}^{(211)}(a) = t_{O}^{a}(k_{2}, k_{1}; k_{1}^{2})$$
 /1.4/

with  $t^a$  denoting the transition matrix due to the potential  $V^a(r)$  which is obtained by cutting off V(r) at r=a. The input to eq. /1.3/ is the conventional S-wave phase function  $\delta_{O}(k,a)$  that satisfies the on-shell phase equation [6]

$$\frac{d\delta_{O}(k,a)}{da} = -k^{-1} V(r) \sin^{2}[ka + \delta_{O}(k,a)]$$
 /1.5/

The pair of equations /1.3/ and /1.5/ should be compared to eqs. /1.1/ - /1.2/ applied to the case  $k_0=k_1$ . In order to solve integral equation /1.1/ at given values of  $k_1$  and  $k_2$ , one has first to integrate eq. /1.2/ once through for each value of parameter q in the range  $q=(0,\infty)$  while to provide, at fixed  $k_1$  and  $k_2$ , complete input to Sobel's equation, a single integration of eq. /1.5/ over the range  $a=(0,\infty)$  will do.

Focussing attention to the phase approach, present paper proposes an explicit solution to the Sobel equation for any partial wave.

#### 2. THE HALF-SHELL VS. ON-SHELL RELATIONSHIP

An integral representation of the S-wave half-shell phase function follows from relationship /1.4/ as  $\begin{bmatrix} 7 \end{bmatrix}$ 

$$\Delta_{O}^{(211)}(a) = \sin \delta_{O}^{(211)}(a) =$$

$$= -\frac{1}{k_{2}} \int_{O}^{a} \sin(k_{2}r) \ V(r) \ u_{O}^{a}(k,r) dr.$$
/2.1/

Here, wave function  $u_0^a(r)$  denotes the particular physical solution to the cut-off problem  $V^a(r)$ , introduced as

$$V^{a}(r) = V(r)$$
,  $r = a$ ,  
= 0 ,  $r > a$ , /2.2/

and is specified by the boundary condition

$$u_O^a(k,r) \rightarrow \sin[kr + \delta_O^a(k)].$$
 /2.3/

The quantity  $\delta_0^a(k) \equiv \delta_0(k,a)$  is the phase function for potential V(r), i.e. the phase shift accumulated by potential  $V^a(r)$ . Owing to the cut-off, asymptotic condition 2.3 can be recast, so as to refer to finite distances, as

$$u_O^a(k,r) = \sin[kr + \delta_O(k,a)]$$
,  $r \ge a$ . /2.4/

Starting from the cut-off point r=a, wave function  $u_O^a(k,r)$  can be continued to the inner region r<a where it coincides but normalization with the physical wave function  $u_O(k,r)$  of problem V(r) which solution, in turn, is uniquely fixed by phase function  $\delta_O(k,r)$ . That wave function vs. phase function relationship is obtained by a standard procedure of the phase approach [6] through parametrizing the wave function by some functions  $c_O(r)$  and  $\omega_O(r)$  as follows

$$u_{o}(k,r) = c_{o}(r) \sin \omega_{o}(r) , \qquad (2.5)$$

$$\frac{du_o(k,r)}{dr} = c_o(r)k \cos \omega_o(r) . \qquad (2.6)$$

A straightforward elimination of c  $_{\rm O}$  establishes the relationship between u  $_{\rm O}$  and  $\omega_{\rm O}$  which can be written in the particular way

$$\tan \left[\omega_{o}(r) - kr\right] = \frac{u'_{o}(r) \sin(kr) - k u_{o}(r)\cos(kr)}{u'_{o}(r) \cos(kr) + k u_{o}(r)\sin(kr)}$$
/2.7/

The r.h.s. of this equation is easily recognized as the well known expression of the tangent of the phase function  $\delta_{o}(k,r)$ . Hence, meaning of parameter  $\omega_{o}(r)$  is recovered as

$$\omega_{O}(k,r) = kr + \delta_{O}(k,r)$$
, mod( $\Pi$ ). /2.8/

Furthermore, by comparing eq. /2.6/ with the first derivative of eq. /2.5/, a differential equation is obtained for the parameter  $c_0(r)$  as

$$\frac{d \ln c_o(r)}{dr} = \frac{d \delta_o(r)}{dr} \cot \omega_o(r) . \qquad (2.9)$$

Solution of this equation

$$\int_{0}^{r} \delta_{0}^{(\prime)}(\rho) \cot \theta \omega_{0}(\rho) d\rho$$

$$c_{0}(k,r) = e^{r_{0}}$$
/2.10/.

involves the free parameter  $r_{o}$  that determines normalization of the wave function. Equations /2.5/ through /2.10/, valid for wave function  $u_{o}(r)$  throughout the range  $(0,\infty)$ , also hold for wave function  $u_{o}^{a}(r)$  in the restricted range r=(0,a). As regards  $u_{o}^{a}(r)$ , integration constant  $r_{o}^{a}$  is fixed by boundary condition /2.4/ which combines with eqs. /2.5/, /2.8/ and /2.10/ to yield

$$r_{0}^{a} = a$$
 . /2.11/

According to the above argument, the properly normalized solution to the cut-off problem, due for insertion in eq. /2.1/, is given for the inner region
by

$$-\int_{0}^{a} \delta_{O}^{(\prime)}(\rho) \cot \theta \omega_{O}(\rho) d\rho$$

$$u_{O}^{a}(k,r) = e^{r} \sin \omega_{O}(r) , r < a. /2.12/$$

On account of eq. /2.1/, the integral representation of the half-off-shell phase function for partial wave  $\ell=0$  in terms of the on-shell phase function rather than the wave function is given by

$$\sin \delta_{o}^{(211)}(a) =$$

$$= -\frac{1}{k_{2}} \int_{0}^{a} \{\sin(k_{2}r) \ V(r) \ e^{-r} \} \int_{0}^{a} (r) d\rho$$
 $\sin \omega_{o}(r) dr$ , /2.13

where abbreviation  $\omega_{\rm O}({\rm r})$  is to be understood in terms of eq. /2.8/. At the same time, eq. /2.13/ furnishes the sought-for explicit solution for Sobel's phase equation /1.3/. Differentiation of e.q. /2.13/ with respect to the variable a, with due regard of its double appearance on the r.h.s., reproduces eq. /1.3/ as it, indeed, should do.

## 3. GENERALIZATION TO HIGHER PARTIAL WAVES

Extension of the method just developed to cases \$>0 is straightforward although not quite trivial. An integral representation of the half-off-shell phase function is given [5] by the equation

$$\sin \delta_{\ell}^{(211)}(a) = -\frac{1}{k_2} \int_{0}^{a} \hat{J}_{\ell}(k_2r) V(r) \tilde{u}_{\ell}^{a}(k_1,r) dr$$
 /3.1/

where the wave function is subject to the boundary condition

$$\tilde{\mathbf{u}}_{\ell}^{a}(\mathbf{k},\mathbf{r}) + \sin\left[\mathbf{k}\mathbf{r} - \ell \frac{\mathbf{I}}{2} + \delta_{\ell}^{a}(\mathbf{k})\right] .$$

$$\uparrow \mathbf{x} + \infty$$

Here again, superscript a refers to the cut-off problem  $V^a(r)$ . Consequently, the asymptotic boundary condition /3.2/ can be recast so as to refer to any finite value of the variable r beyond the cut-off point r=a. To do so, one has to consider that wave function  $\tilde{u}^a_{\ell}(r)$ : (i) should satisfy for r≥a the force free partial wave equation; (ii) should imply  $\delta^a_{\ell}$  as the phase shift in the  $\ell$ th partial wave; (iii) should reproduce the asymptotical behaviour fixed by eq. /3.2/. The expression

$$\tilde{u}_{\ell}^{a}(k,r) = \cos \delta_{\ell}^{a}(k) \hat{j}_{\ell}(kr) - \sin \delta_{\ell}^{a}(k) \hat{n}_{\ell}(kr) , \quad r \geq a , \qquad /3.3/$$

is easily seen to fulfil requirements (i) through (iii), by considering the properties of the Riccati-Bessel functions involved.

The next step of the argument is continuation of wave function  $\tilde{u}_{\ell}^{a}(r)$  into the inner region r<a. To this end,  $\tilde{u}_{\ell}^{a}(r)$  will be separeted into two r-dependent factors such as an a-independent phase factor and an amplitude function that carries the a-dependence implied in boundary condition /3.2/. This factorization is conveniently done by the familiar parametrization procedure of Calogero [6] as

$$\tilde{\mathbf{u}}_{\ell}^{\mathbf{a}}(\mathbf{k},\mathbf{r}) = \mathbf{c}_{\ell}^{\mathbf{a}}(\mathbf{r})\{\cos\theta_{\ell}^{\mathbf{a}}(\mathbf{r}) \ \hat{\mathbf{j}}_{\ell}(\mathbf{k}\mathbf{r}) - \sin\theta_{\ell}^{\mathbf{a}}(\mathbf{r}) \ \hat{\mathbf{n}}_{\ell}(\mathbf{k}\mathbf{r})\}$$

$$/3.4/$$

and

$$\frac{d \tilde{u}_{\ell}^{a}(k,r)}{dr} = k c_{\ell}^{a}(r) \{\cos\theta_{\ell}^{a}(r) \hat{j}_{\ell}^{(\prime)}(kr) - \sin\theta_{\ell}^{a}(r) \hat{n}_{\ell}^{(\prime)}(kr) \}.$$
 /3.5/

In order to extract physical meaning for parameters  $c^a_\ell$  and  $\theta^a_\ell$ , one has to resolve this system of equations for  $\theta^a_\ell$ . Then, one has the expression

$$\tan \theta_{\ell}^{a}(r) = \frac{\tilde{u}_{\ell}^{a(\prime)}(r) \, \hat{j}_{\ell}(kr) - k \, \tilde{u}_{\ell}^{a}(r) \, \hat{j}_{\ell}(kr)}{\tilde{u}_{\ell}^{a(\prime)}(r) \, \hat{n}_{\ell}(kr) - k \, \tilde{u}_{\ell}^{a}(r) \, \hat{n}_{\ell}(kr)}, \qquad (3.6)$$

which is seen to be independent of the particular normalization of the wave function involved. In view of the proportionality, for r<a, of the physical solutions  $\tilde{u}_{\ell}^{a}(r)$  and  $\tilde{u}_{\ell}(r)$ , eq. /3.6/ proves at once the equivalence

$$\Theta_{\ell}^{a}(r) = \delta_{\ell}(r), \quad mod(\Pi), \quad r \leq a.$$
 /3.7/

Parameter  $\theta_{\ell}^{a}(r)$  coincides thus inside the cut-off point with the phase function of the problem V(r). As regards the other parameter, a differential equation can be extracted by combining eqs. /3.4/ and /3.5/ as

$$\frac{\mathrm{d} \ln c_{\ell}^{a}(r)}{\mathrm{d}r} = \frac{\mathrm{d} \delta_{\ell}(r)}{\mathrm{d}r} \tau_{\ell}^{-1}(r), \qquad r < a, \qquad /3.8/$$

where the notation

$$\tau_{\ell}^{-1}(r) = \frac{\sin\delta_{\ell}(r) \hat{j}_{\ell}(kr) + \cos\delta_{\ell}(r) \hat{n}_{\ell}(kr)}{\cos\delta_{\ell}(r) \hat{j}_{\ell}(kr) - \sin\delta_{\ell}(r) \hat{n}_{\ell}(kr)}$$
/3.9/

was introduced. The solution of eq. /3.8/ is given by

$$\int_{\ell}^{r} \delta_{\ell}^{(\prime)}(\rho) \tau_{\ell}^{-1}(\rho) d\rho$$

$$c_{\ell}^{a}(r) = e^{r} \ell_{\ell}^{(a)}$$
(3.10/

involving the constant of integration  $r_{\ell}(a)$  that is responsible for the normalization of wave function  $\tilde{u}_{\ell}^a(r)$ . Note that boundary condition /3.3/ holds at and beyond the cut-off point r=a while the parametrization procedure implied by eq. /3.4/ through /3.10/ is valid at and inside the cut-off. Therefore, by putting just r=a in both equations /3.3/ and /3.4/, condition /3.3/ is reworded for incorporation into eq. /3.4/ as

$$c_{\ell}^{a}(a) = 1$$
 . (3.11/

Hence,  $r_{\ell}(a)=a$  and thus parameter  $c_{\ell}^a$  is finally fixed for the inner region as

$$c_{\ell}^{a}(r) = e^{\int_{r}^{a} \delta_{\ell}^{(\prime)}(\rho) \tau_{\ell}^{-1}(\rho) d\rho}$$

$$(c_{\ell}^{a}(r) = e^{\int_{r}^{a} \delta_{\ell}^{(\prime)}(\rho) \tau_{\ell}^{-1}(\rho) d\rho} - \int_{r}^{a} \delta_{\ell}^{(\prime)}(\rho) \tau_{\ell}^{-1}(\rho) d\rho$$

Equations /3.1/, /3.4/ and /3.12/ combine now into the explicit expression of the half-off-shell phase function in terms of the on-shell phase function in the  $\ell$ th partial wave as

$$sin\delta_{\ell}(k_{2}, k_{1}; k_{1}^{2}; a) =$$

$$= -\frac{1}{k_{2}} \int_{0}^{a} \hat{j}_{\ell}(k_{2}r) V(r) c_{\ell}^{a}(k_{1},r) \delta_{\ell}(k_{1},r) dr,$$
/3.13/

where the notation

$$\sigma_{\ell}(\mathbf{k},\mathbf{r}) \equiv \cos\delta_{\ell}(\mathbf{k},\mathbf{r}) \hat{\mathbf{j}}_{\ell}(\mathbf{k}\mathbf{r}) - \sin\delta_{\ell}(\mathbf{k},\mathbf{r}) \hat{\mathbf{n}}_{\ell}(\mathbf{k}\mathbf{r})$$
 /3.14/

for the phase factor was introduced. If one prefers, also potential V(r) can be eliminated from formula /3.13/ by means of the phase equation [7]

$$\frac{\mathrm{d}\delta_{\ell}(k,r)}{\mathrm{d}r} = -\frac{1}{k} \, \mathrm{V}(r) \, \sigma_{\ell}^2(k,r). \qquad (3.15)$$

In doing so, the half-shell versus on-shell relationship /3.12/ - /3.14/ for the phase functions can be reworded as

$$sin\delta_{\ell}(k_{2}, k_{1}; k_{1}^{2}; a) =$$

$$= \frac{k_{1}}{k_{2}} \int_{0}^{a} \hat{j}_{\ell}(k_{2}r) \frac{d\delta_{\ell}(k_{1},r)}{dr} \frac{c_{\ell}^{a}(k_{1},r)}{\sigma_{\ell}(k_{1},r)} dr, \qquad (3.16)$$

with the notations of eqs. /3.12/ and /3.14/.

Just as in the S-wave case, integral representation /3.13/ of the half-shell phase can be converted into a differential equation. Differentiating eq. /3.13/ with respect to the cut-off distance a, one has first to calculate the derivative of parameter  $c_{\ell}^a$  which is worth writing down here /and comparing to eq. /3.8//:

$$\frac{\mathrm{d} \ c_{\ell}^{\mathrm{a}}(\mathrm{r})}{\mathrm{d} \mathrm{a}} = \frac{\mathrm{d} \ \delta_{\ell}(\mathrm{a})}{\mathrm{d} \mathrm{a}} \quad \tau_{\ell}^{-1}(\mathrm{a}) \ c_{\ell}^{\mathrm{a}}(\mathrm{r}) \ . \tag{3.17}$$

With this equation in mind, one obtains in a straightforward way the non-linear differential equation for the half-shell phase function:

$$\frac{\mathrm{d} \sin \delta_{\ell}^{(211)}(a)}{\mathrm{d} a} =$$

$$= \hat{j}_{\ell}(k_{2}a) \ V(a) \ \sigma_{\ell}(k_{1},a) - \frac{d \ \delta_{\ell}(k_{1},a)}{da} \ \tau_{\ell}^{-1}(a) \ \sin \delta_{\ell}^{(211)}(a) \ . \tag{3.18}$$

This equation can be cast in new forms in different ways. One can eliminate the potential by means of phase equation /3.15/ or, conversely, replace the derivative  $\delta_{\ell}^{(\,\prime\,)}(a)$  by means of the potential. Proceeding with the latter choice, eq. /3.18/ becomes

$$\frac{\mathrm{d} \, \sin \delta_{\ell}^{(211)}(a)}{\mathrm{d} a} = - \, V(a) \, \sigma_{\ell}(k_{1}, a)$$

$$\{k_{2}^{-1} \, \hat{j}_{\ell}(k_{2}a) - k_{1}^{-1} \, \kappa_{\ell}(k_{1}, a) \, \sin \delta_{\ell}^{(211)}(a)\} , \qquad /3.19/$$

with the notation

$$\kappa_{\ell}(\mathbf{k},\mathbf{r}) \equiv \sin\delta_{\ell}(\mathbf{k},\mathbf{r}) \, \hat{\mathbf{j}}_{\ell}(\mathbf{k}\mathbf{r}) + \cos\delta_{\ell}(\mathbf{k},\mathbf{r}) \, \hat{\mathbf{n}}_{\ell}(\mathbf{k},\mathbf{r}) , \qquad (3.20)$$

This equation is, however, identical with Sobel's general half-off-shell phase equation [8], as it, indeed, should be so.

Summarizing the above considerations, one sees that explicit formulae have been derived for the half-off-shell phase functions in terms of the on-shell phase functions. Simultaneously, the general Sobel equation has been rederived. For this first order differential equation one has thus found the exact solution. As regards the two-body input to the Karlsson-Zeiger three-body equations, the half-shell phases are obtained from the half-shell phase functions  $\delta^{(211)}(a)$  by simply going to the limit  $a^{+\infty}$ .

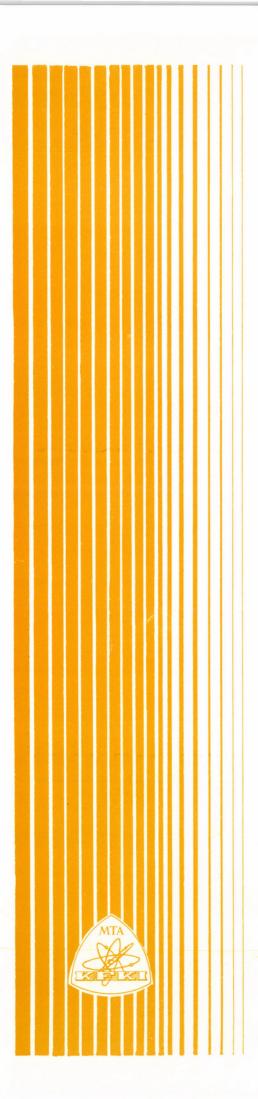
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62 430



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